

# Math 245C Lecture 28 Notes

Daniel Raban

June 5, 2019

## 1 Distributions of Differences

### 1.1 Differences of functions in Sobolev spaces

Let  $\Omega \subseteq \mathbb{R}^d$  be an open set. If  $A \subseteq \mathbb{R}^d$ ,  $f : A \rightarrow \mathbb{R}$  and  $y \in \mathbb{R}^d$  we set  $f_y(x) = f(x - y)$  for  $x \in A + y$ . If  $\phi \in C_c^\infty(\Omega)$ , let  $O_\phi = \{y \in \mathbb{R}^d : y + \text{supp}(\phi) \subseteq \Omega\}$ .

**Proposition 1.1.** *Let  $\phi \in C_c^\infty(\Omega)$  and  $y \in \mathbb{R}^d$ . Then  $K = \bigcup_{y \in [0,1]}(ty + \text{supp}(\phi))$  is compact.*

*Proof.* Set  $f(t, z) = ty + z$ .  $f : \mathbb{R}^{d+1} \rightarrow \mathbb{R}^d$  is continuous, and  $K = f([0, 1] \times \text{supp}(\phi))$  is compact as the image of a compact set by a continuous function.  $\square$

**Theorem 1.1.** *Let  $T \in \mathcal{D}'(\Omega)$ , and let  $y \in \mathbb{R}^d$ .*

1. *If  $\phi \in C_c^\infty(\Omega)$  and  $ty + \text{supp}(\phi) \subseteq \Omega$  for all  $t \in [0, 1]$ , then*

$$T(\phi_y) = T(\phi) = \int_0^1 \sum_{j=1}^d y_j \partial_j T(\phi_{ty}) dt.$$

2. *If  $f \in W_{\text{loc}}^{1,1}(\mathbb{R}^d)$ , then for a.e.  $x \in \mathbb{R}^d$ ,*

$$f(x + y) - f(x) = \int_0^1 \nabla f(x + ty) \cdot y dt.$$

In the second case, if we could show that  $\frac{d}{dt}T(\phi_{ty}) = \nabla T(\phi_{ty}) \cdot y$  and that this derivative is continuous, we could just use the fundamental theorem of calculus.

*Proof.* Set  $K = \bigcup_{t \in [0,1]}(ty + \text{supp}(\phi))$ . Then  $K \subseteq \Omega$  is compact. For  $x \in \mathbb{R}^d$  and  $h \neq 0$ ,

$$L_h(x) := \frac{\phi(x - (t+h)y) - \phi(x - ty)}{h} = - \int_0^1 \nabla \phi(x - ty - \tau hy) \cdot y d\tau.$$

Note that  $L_h \in C_c^\infty(\Omega)$  if  $0 < |h| \ll 1$ , and

$$\lim_{h \rightarrow 0} H_h(x) = \nabla \phi(x - ty) \cdot y =: L_0(x).$$

Also,  $(L_h)_h$  converges to  $L_0$  in  $C_c^\infty(\Omega)$ . Thus,

$$\begin{aligned} \frac{d}{dt} T(\phi_{ty}) &= \lim_{h \rightarrow 0} T(L_h) = T(L_0) = T(-\nabla \phi(x - ty) \cdot y) \\ &= - \sum_{j=1}^d y_j T(\partial_j \phi(\cdot - ty)) = \sum_{j=1}^d y_j \partial_j T(\phi(\cdot - ty)) \\ &= \sum_{j=1}^d y_j \partial_j T(\phi_{ty}). \end{aligned}$$

As  $t \rightarrow \partial_j T(\phi_{t,y})$  is continuous, we conclude that  $t \rightarrow \frac{d}{dt} T(\phi_{ty})$  is continuous. So we get

$$T(\phi_y) - T(\phi) = \int_0^1 \frac{d}{dt} (T(\phi_{ty})) dt = \int_0^1 \nabla T(\phi_{ty}) \cdot y dt.$$

For the second statement, let  $f \in W_{\text{loc}}^{1,1}$ , and set

$$T(\phi) = \int_{\mathbb{R}^d} \phi(x) f(x) dx.$$

Then  $T \in \mathcal{D}'(\Omega)$ , and  $\partial_j T(\phi) = -T(\partial_j \phi) = - \int_{\mathbb{R}^d} \partial_j \phi f$ . So

$$\partial_j T(\phi) = \int_{\mathbb{R}^d} \phi(x) \partial_j f(x) dx.$$

By the first statement,

$$\int_{\mathbb{R}^d} (\phi_y(x) - \phi(x)) f(x) dx = \int_0^1 \int_{\mathbb{R}^d} \sum_{j=1}^d y_j \phi_{ty}(x) \partial_j f(x) dx dt.$$

The left hand side is

$$\int_{\mathbb{R}^d} (\phi(x - y) - \phi(x)) f(x) dx,$$

and the left hand side is

$$\int_0^1 \int_{\mathbb{R}^d} \sum_{j=1}^d y_j \phi(x - ty) \partial_j f(x) dx dt.$$

If we make the change of variables  $z = z - y$ , then

$$\int_{\mathbb{R}^d} \phi(z)(f(z+y) - f(z)) dz = \int_0^1 \int_{\mathbb{R}^d} \sum_{j=1}^d y_j \phi(z) \partial_j f(z+ty) dz dt.$$

Since  $\phi$  is of compact support and  $\partial_j f \in L^1_{\text{loc}}$  we check that we can apply Fubini's theorem to conclude that

$$\int_{\mathbb{R}^d} \phi(z)(f(z+y) - f(z)) dz = \int_{\mathbb{R}^d} \phi(z) \left( \int_0^1 \nabla f(z+ty) \cdot y dt \right) dz.$$

By Hölder's inequality, this implies that  $z \mapsto \int_0^1 \nabla f(z+ty) \cdot y dt \in L^1_{\text{loc}}(\mathbb{R}^d)$ , and

$$f(z+y) - f(z) = \int_0^1 \nabla f(z+ty) \cdot y dt$$

for a.e.  $z \in \mathbb{R}^d$ . □

**Remark 1.1.** Let  $f \in C^1(\Omega)$ , and set

$$T(\phi) = \int_{\Omega} f(x)\phi(x) dx, \quad \phi \in C_c^\infty(\Omega).$$

Then  $T \in \mathcal{D}'(\Omega)$ , and

$$\partial_j T(\phi) = \int_{\Omega} \frac{\partial f}{\partial x_j}(x)\phi(x) dx,$$

where  $\frac{\partial f}{\partial x_j}$  is the pointwise derivative.

This has a converse.

**Theorem 1.2.** Let  $g_1, \dots, g_d \in C(\Omega)$ , and let  $T \in \mathcal{D}'(\Omega)$  be such that  $\partial_j T = g_j$  for  $j = 1, \dots, d$ . Then there exists  $f \in C^1(\Omega)$  such that

$$T(\phi) = \int_{\Omega} f(x)\phi(x) dx, \quad \phi \in C_c^\infty(\Omega).$$

Then

$$g_j = \frac{\partial f}{\partial x_j}.$$

**Corollary 1.1.** If  $\Omega$  is connected,  $T \in \mathcal{D}'(\Omega)$ , and  $\partial_j T = 0$  for  $j = 1, \dots, d$ , then there exists  $C \in \mathbb{R}$  such that

$$T(\phi) = C \int_{\Omega} \phi(x) dx, \quad \forall \phi \in C_c^\infty(\Omega).$$